

**EXISTENCE AND UNIQUENESS OF SOLUTIONS  
FOR A SYSTEM OF FRACTIONAL  
DIFFERENTIAL EQUATIONS <sup>1</sup>**

**Yong Zhou**

**Abstract**

In this paper, the initial value problem is discussed for a system of fractional differential equations and new criteria on existence and uniqueness of solutions are obtained.

*2000 Mathematics Subject Classification:* 34K05, 34A12, 34A40

*Key Words and Phrases:* fractional differential equations, existence, uniqueness, Caputo's derivative

**1. Introduction**

In the recent years, many works have been devoted to the study of initial value problems for fractional differential equations. See, for example papers [1] – [10] and the references therein. In fact, the differential equations involving differential operators of fractional order  $0 < \alpha < 1$ , appear to be important in modelling several physical phenomena [11] – [19].

In this paper, we study the initial value problem (IVP) for a system of fractional differential equations

$$\begin{cases} D^\alpha x(t) = f(t, x(t)) \\ x(t_0) = x_0 \end{cases}, \quad (1)$$

---

<sup>1</sup> Research supported by National Natural Science Foundation of P.R. China and Research Fund of Hunan Provincial Education Department (08A071).

where the fractional derivative is in the sense of Caputo's definition, the function  $f(t, x) : R \times R^n \rightarrow R^n$  is called vector field, and the dimension  $n \geq 1$ . Particularly,  $R^n$  endowed a proper norm  $\|\cdot\|$  becomes a complete metric space.

Caputo's derivative of order  $\alpha \in (0, 1)$  and with the lower limit  $t_0$  is defined by

$$D^\alpha x(t) = \frac{1}{\Gamma(1-\alpha)} \int_{t_0}^t (t-s)^{-\alpha} x'(s) ds.$$

Let

$$J = [t_0 - a, t_0 + a], B = \{x \in R^n \mid \|x - x_0\| \leq b\},$$

$$E = \{(t, x) \in R \times R^n \mid t \in J, x \in B\}.$$

A function  $x \in C^1(J, R^n)$  is said to be a solution of (1) if  $x$  satisfies the equation  $D^\alpha x(t) = f(t, x(t))$  a.e.  $J$ , and the condition  $x(t_0) = x_0$ .

In 2008, Lakshmikantham and Vatsala [3] give the following existence result for IVP (1).

**THEOREM A.** ([3]) Assume that  $f \in C([t_0, t_0 + a] \times B_1, R)$  and let  $|f(t, x)| \leq M$  on  $[t_0, t_0 + a] \times B_1$ , where  $B_1 = \{x \in R \mid |x - x_0| \leq b\}$ . Then the IVP (1) possesses at least one solution  $x(t)$  on  $[t_0, t_0 + h]$ , where  $h = \min\{a, [\frac{b}{M}\Gamma(\alpha + 1)]^{1/\alpha}\}$ ,  $0 < \alpha < 1$ .

In 2007, Lin [4] obtained the following local existence results for IVP (1).

**THEOREM B.** ([4]) Assume that the function  $f : E \rightarrow R^n$  satisfies the following conditions:

(H<sub>1</sub>)  $f(t, x)$  is Lebesgue measurable with respect to  $t$  on  $J$ ;

(H<sub>2</sub>)  $f(t, x)$  is continuous with respect to  $x$  on  $B$ ;

(H<sub>3</sub>) there exists a real-valued function  $m(t) \in L^2(J)$  such that

$$\|f(t, x)\| \leq m(t), \text{ for almost every } t \in J \text{ and all } x \in B.$$

Then, for  $\frac{1}{2} < \alpha < 1$ , there at least exists a solution of the IVP (1) on the interval  $[t_0 - h, t_0 + h]$  for some positive number  $h$ .

**THEOREM C.** ([4]) All the assumptions of Theorem B hold. Assume that (H<sub>4</sub>) there exists a real-valued function  $\mu(t) \in L^4(J)$  such that

$$\|f(t, x) - f(t, y)\| \leq \mu(t)\|x - y\|, \text{ for almost every } t \in J \text{ and all } x, y \in B.$$

Then, for  $\frac{1}{2} < \alpha < 1$ , there exists a unique solution of the IVP (1) on  $[t_0 - h, t_0 + h]$  with some positive number  $h$ .

In Remark 2.3 of [4], it is mentioned that Theorems B and C could be generalized to the case where  $\alpha \in (0, \frac{1}{2})$  provided that  $m(t)$  is bounded on  $[t_0 - a, t_0 + a]$ .

In this paper, by using some different methods and new techniques, we obtain various criteria on existence and uniqueness of solutions for IVP (1). Our results improve/extend Theorems A, B and C. In particular, we remove the restrictive conditions that  $\|f(t, x)\| \leq M$  in Theorem A and that  $\alpha > \frac{1}{2}$  in Theorems B and C, and relax the hypothesis (H<sub>3</sub>) and (H<sub>4</sub>).

### 3. Main Results

**THEOREM 1.** *Assume that the function  $f : E \rightarrow R^n$  satisfies the following conditions of Carathéodory type:*

- (i)  $f(t, x)$  is Lebesgue measurable with respect to  $t$  on  $J$ ;
- (ii)  $f(t, x)$  is continuous with respect to  $x$  on  $B$ ;
- (iii) there exist a constant  $\beta \in (0, \alpha)$  and a real-valued function  $m(t) \in L^{\frac{1}{\beta}}(J)$  such that  $\|f(t, x)\| \leq m(t)$ , for almost every  $t \in J$  and all  $x \in B$ .

Then, for  $\alpha \in (0, 1)$ , there at least exists a solution of the IVP (1) on the interval  $[t_0 - h, t_0 + h]$ , where  $h = \min\{a, [\frac{b\Gamma(\alpha)}{M}(\frac{\alpha-\beta}{1-\beta})^{1-\beta}]^{\frac{1}{\alpha-\beta}}\}$  and  $M = (\int_{t_0}^{t_0+a} (m(s))^{\frac{1}{\beta}} ds)^{\beta}$ .

**P r o o f.** The IVP (1) for the case where  $t \in [t_0, t_0 + h]$  are only discussed. Similar approach could be used to verify the case where  $t \in [t_0 - h, t_0]$ . We know that  $f(t, x(t))$  is Lebesgue measurable in  $[t_0, t_0 + h]$  according to the conditions (i) and (ii). Direct calculation gives that  $(t - s)^{\alpha-1} \in L^{\frac{1}{1-\beta}}[t_0, t]$ , for  $t \in [t_0, t_0 + h]$ . In light of the Hölder inequality, we obtain that  $(t - s)^{\alpha-1} f(s, x(s))$  is Lebesgue integrable with respect to  $s \in [t_0, t]$  for all  $t \in [t_0, t_0 + h]$ , and

$$\int_{t_0}^t \|(t - s)^{\alpha-1} f(s, x(s))\| ds \leq \left( \int_{t_0}^t ((t - s)^{\alpha-1})^{\frac{1}{1-\beta}} ds \right)^{1-\beta} \left( \int_{t_0}^t (m(s))^{\frac{1}{\beta}} ds \right)^{\beta}.$$

For  $x \in C([t_0, t_0 + h], R^n)$ , define norm of  $\|x\|_* = \sup_{s \in [t_0, t_0 + h]} \|x(s)\|$ . Then  $C([t_0, t_0 + h], R^n)$  with  $\|\cdot\|_*$  is a Banach space. Let  $\Omega = \{x \in C([t_0, t_0 + h], R^n) : \|x - x_0\|_* \leq b\}$ . Then,  $\Omega$  is a closed, bounded and convex subset of  $C([t_0, t_0 + h], R^n)$ .

We now define a mapping on  $\Omega$  as follows. For an element  $x \in \Omega$ , let

$$(Tx)(t) = x_0 + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} f(s, x(s)) ds, \quad t \in [t_0, t_0 + h].$$

a) We shall show that for any  $x \in \Omega$ ,  $Tx \in \Omega$ .

In fact, by using the Hölder inequality and the condition (iii), we get

$$\begin{aligned} \|(Tx)(t) - x_0\| &\leq \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} m(s) ds \\ &\leq \frac{1}{\Gamma(\alpha)} \left( \int_{t_0}^t ((t-s)^{\alpha-1})^{\frac{1}{1-\beta}} ds \right)^{1-\beta} \left( \int_{t_0}^t (m(s))^{\frac{1}{\beta}} ds \right)^{\beta} \\ &\leq \frac{1}{\Gamma(\alpha)} \left( \frac{1-\beta}{\alpha-\beta} \right)^{1-\beta} (t-t_0)^{\alpha-\beta} \left( \int_{t_0}^{t_0+h} (m(s))^{\frac{1}{\beta}} ds \right)^{\beta} \\ &\leq \frac{1}{\Gamma(\alpha)} \left( \frac{1-\beta}{\alpha-\beta} \right)^{1-\beta} h^{\alpha-\beta} M \\ &\leq b, \quad \text{for } t \in [t_0, t_0 + h]. \end{aligned}$$

This means that  $\|Tx - x_0\|_* \leq b$ . Hence,  $T$  is a mapping from  $\Omega$  into itself.

b) We now show that  $T$  is completely continuous.

First, we will show that  $T$  is continuous. For any  $x_m, x \in \Omega$ ,  $m = 1, 2, \dots$  with  $\lim_{m \rightarrow \infty} \|x_m - x\|_* = 0$ , we get

$$\lim_{m \rightarrow \infty} x_m(t) = x(t), \quad \text{for } t \in [t_0, t_0 + h].$$

Thus, by the condition (ii), we have

$$\lim_{m \rightarrow \infty} f(t, x_m(t)) = f(t, x(t)), \quad \text{for } t \in [t_0, t_0 + h].$$

So, we can conclude that

$$\sup_{s \in [t_0, t_0 + h]} \|f(s, x_m(s)) - f(s, x(s))\| \rightarrow 0, \quad \text{as } m \rightarrow \infty.$$

On the other hand,

$$\begin{aligned} \|(Tx_m)(t) - T(x)(t)\| &= \frac{1}{\Gamma(\alpha)} \left\| \int_{t_0}^t (t-s)^{\alpha-1} [f(s, x_m(s)) - f(s, x(s))] ds \right\| \\ &\leq \frac{h^\alpha}{\Gamma(\alpha+1)} \sup_{s \in [t_0, t_0 + h]} \|f(s, x_m(s)) - f(s, x(s))\|, \end{aligned}$$

which implies

$$\|Tx_m - Tx\|_* \leq \frac{h^\alpha}{\Gamma(\alpha + 1)} \sup_{s \in [t_0, t_0+h]} \|f(s, x_m(s)) - f(s, x(s))\|.$$

Hence,

$$\|Tx_m - Tx\|_* \rightarrow 0 \text{ as } m \rightarrow \infty.$$

This means that  $T$  is continuous.

Next, we show  $T\Omega$  is relatively compact. It suffices to show that the family of functions  $\{Tx : x \in \Omega\}$  is uniformly bounded and equicontinuous on  $[t_0, t_0 + h]$ .

For  $x \in \Omega$ , we get

$$\|Tx\|_* \leq \|x_0\| + b,$$

which means that  $\{Tx : x \in \Omega\}$  is uniformly bounded.

On the other hand, for any  $t_1, t_2 \in [t_0, t_0 + h], t_1 < t_2$ , by using the Hölder inequality, we have

$$\begin{aligned} & \| (Tx)(t_2) - (Tx)(t_1) \| \\ &= \frac{1}{\Gamma(\alpha)} \left\| \int_{t_0}^{t_1} ((t_2 - s)^{\alpha-1} - (t_1 - s)^{\alpha-1}) f(s, x(s)) ds \right. \\ & \quad \left. + \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} f(s, x(s)) ds \right\| \\ &\leq \frac{1}{\Gamma(\alpha)} \int_{t_0}^{t_1} \|((t_2 - s)^{\alpha-1} - (t_1 - s)^{\alpha-1}) f(s, x(s))\| ds \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} \|(t_2 - s)^{\alpha-1} f(s, x(s))\| ds \\ &\leq \frac{1}{\Gamma(\alpha)} \int_{t_0}^{t_1} ((t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1}) m(s) ds \\ & \quad + \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} m(s) ds \\ &\leq \frac{1}{\Gamma(\alpha)} \left( \int_{t_0}^{t_1} ((t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1})^{\frac{1}{1-\beta}} ds \right)^{1-\beta} \left( \int_{t_0}^{t_1} (m(s))^{\frac{1}{\beta}} ds \right)^{\beta} \end{aligned}$$

$$\begin{aligned}
& + \frac{1}{\Gamma(\alpha)} \left( \int_{t_1}^{t_2} ((t_2 - s)^{\alpha-1})^{\frac{1}{1-\beta}} ds \right)^{1-\beta} \left( \int_{t_1}^{t_2} (m(s))^{\frac{1}{\beta}} ds \right)^{\beta} \\
& \leq \frac{1}{\Gamma(\alpha)} \left( \int_{t_0}^{t_1} ((t_1 - s)^{\frac{\alpha-1}{1-\beta}} - (t_2 - s)^{\frac{\alpha-1}{1-\beta}}) ds \right)^{1-\beta} \left( \int_{t_0}^{t_0+h} (m(s))^{\frac{1}{\beta}} ds \right)^{\beta} \\
& + \frac{1}{\Gamma(\alpha)} \left( \int_{t_1}^{t_2} (t_2 - s)^{\frac{\alpha-1}{1-\beta}} ds \right)^{1-\beta} \left( \int_{t_0}^{t_0+h} (m(s))^{\frac{1}{\beta}} ds \right)^{\beta} \\
& \leq \frac{M}{\Gamma(\alpha)} \left( \frac{1-\beta}{\alpha-\beta} \right)^{1-\beta} \left( (t_1 - t_0)^{\frac{\alpha-1}{1-\beta}+1} + (t_2 - t_1)^{\frac{\alpha-1}{1-\beta}+1} \right. \\
& \quad \left. - (t_2 - t_0)^{\frac{\alpha-1}{1-\beta}+1} \right)^{1-\beta} + \frac{M}{\Gamma(\alpha)} \left( \frac{1-\beta}{\alpha-\beta} \right)^{1-\beta} \left( (t_2 - t_1)^{\frac{\alpha-1}{1-\beta}+1} \right)^{1-\beta} \\
& \leq \frac{2M}{\Gamma(\alpha)} \left( \frac{1-\beta}{\alpha-\beta} \right)^{1-\beta} (t_2 - t_1)^{\alpha-\beta}.
\end{aligned}$$

As  $t_1 \rightarrow t_2$  the right-hand side of the above inequality tends to zero. Therefore  $\{Tx : x \in \Omega\}$  is equicontinuous on  $[t_0, t_0+h]$ , and hence  $T\Omega$  is relatively compact. By Schauder's fixed point theorem, there is a  $x^* \in \Omega$  such that  $Tx^* = x^*$ , that is

$$x^*(t) = x_0 + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} f(s, x^*(s)) ds, \quad t \in [t_0, t_0+h].$$

It is easy to see that  $x^*$  is a solution of IVP (1) on  $[t_0, t_0+h]$ . This completes the proof.  $\blacksquare$

**COROLLARY 1.** *Let  $f \in C(J \times B, R^n)$ . Then, for  $\alpha \in (0, 1)$ , there at least exists a solution of the IVP (1) on the interval  $[t_0 - h', t_0 + h']$ , where  $h' = \min\{a, [\frac{b}{M'} \Gamma(\alpha + 1)]^{\frac{1}{\alpha}}\}$  and  $M' = \sup_{(t,x) \in J \times B} f(t, x)$ .*

The proof of Corollary 1 is similar to that of Theorem 1, it is therefore omitted.

**REMARK 1.** Theorem 1 improves essentially Theorem B by removing the restrictive condition that  $\alpha > \frac{1}{2}$ , and relaxing the condition  $(H_3)$ . Corollary 1 extends Theorem A.

**THEOREM 2.** *All the assumptions of Theorem 1 hold. Assume that*

(iv) there exist constant  $\gamma \in (0, \alpha)$  and a real-valued function  $\mu(t) \in L^{\frac{1}{\gamma}}[t_0, t_0 + a]$  such that  $\|f(t, x) - f(t, y)\| \leq \mu(t)\|x - y\|$ , for almost every  $t \in J$  and all  $x, y \in B$ .

Then there exists a unique solution of IVP (1) on  $[t_0 - h_1, t_0 + h_1]$ , where  $h_1 < \min \left\{ a, h, \left[ \frac{\Gamma(\alpha)}{M_1} \left( \frac{\alpha - \gamma}{1 - \gamma} \right)^{1-\gamma} \right]^{\frac{1}{\alpha-\gamma}} \right\}$  and  $M_1 = \left( \int_{t_0}^{t_0+a} (\mu(s))^{\frac{1}{\gamma}} ds \right)^{\gamma}$ .

**P r o o f.** Let  $\Omega = \{x \in C([t_0, t_0 + h_1], R^n) : \|x - x_0\|_* \leq b\}$ . For an element  $x \in \Omega$ , let

$$(Tx)(t) = x_0 + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} f(s, x(s)) ds, \quad t \in [t_0, t_0 + h_1].$$

Similarly, we can prove that  $T\Omega \subseteq \Omega$  and  $(Tx)(t)$  is continuous on  $[t_0, t_0 + h_1]$ . Now we shall show that operator  $T$  is a contraction operator on  $\Omega$ .

In fact, for  $x, y \in \Omega$ , we have

$$\begin{aligned} & \| (Tx)(t) - (Ty)(t) \| \\ & \leq \frac{1}{\Gamma(\alpha)} \left( \int_{t_0}^t (t-s)^{\alpha-1} \mu(s) ds \right) \max_{s \in [t_0, t_0+h_1]} \|x(s) - y(s)\| \\ & \leq \frac{1}{\Gamma(\alpha)} \left( \int_{t_0}^t (t-s)^{\alpha-1} \mu(s) ds \right) \|x - y\|_* \\ & \leq \frac{1}{\Gamma(\alpha)} \left( \int_{t_0}^t ((t-s)^{\alpha-1})^{\frac{1}{1-\gamma}} ds \right)^{1-\gamma} \left( \int_{t_0}^t (\mu(s))^{\frac{1}{\gamma}} ds \right)^{\gamma} \|x - y\|_* \\ & \leq \frac{1}{\Gamma(\alpha)} \left( \frac{1-\gamma}{\alpha-\gamma} \right)^{1-\gamma} (t-t_0)^{\alpha-\gamma} \left( \int_{t_0}^{t_0+h_1} (\mu(s))^{\frac{1}{\gamma}} ds \right)^{\gamma} \|x - y\|_* \\ & \leq \frac{M_1}{\Gamma(\alpha)} \left( \frac{1-\gamma}{\alpha-\gamma} \right)^{1-\gamma} h_1^{\alpha-\gamma} \|x - y\|_*, \quad \text{for } t \in [t_0, t_0 + h_1]. \end{aligned}$$

This implies that

$$\|Tx - Ty\|_* \leq c \|x - y\|_*$$

where  $c = \frac{M_1}{\Gamma(\alpha)} \left( \frac{1-\gamma}{\alpha-\gamma} \right)^{1-\gamma} h_1^{\alpha-\gamma} \in (0, 1)$ , which proves that  $T$  is a contraction mapping. In view of the contraction mapping principle,  $T$  has the unique fixed point  $x$ , which is obviously a solution of IVP (1) on  $[t_0, t_0 + h_1]$ . The proof is complete.  $\blacksquare$

REMARK 2. Theorem 2 improves essentially Theorem C by removing the restrictive condition that  $\alpha > \frac{1}{2}$ , and relaxing the condition (H<sub>4</sub>).

COROLLARY 2. Let  $f \in C(J \times B, R^n)$ . Assume that there exists a constant  $L > 0$  such that  $\|f(t, x) - f(t, y)\| \leq L\|x - y\|$ , for almost every  $t \in J$  and all  $x, y \in B$ . Then, for  $\alpha \in (0, 1)$ , there exists a unique solution of IVP (1) on the interval  $[t_0 - h'_1, t_0 + h'_1]$ , where  $h'_1 < \min\{a, h', [\frac{1}{L}\Gamma(\alpha+1)]^{\frac{1}{\alpha}}\}$ .

The proof of Corollary 2 is similar to that of Theorem 2, it is therefore omitted.

THEOREM 3. Assume that the condition (iv) of Theorem 2 holds. If the solutions of IVP (1) exist on  $[t_0 - h, t_0 + h]$ , then the solution of IVP (1) is unique, where  $h < \min\{a, [\frac{\Gamma(\alpha)}{M_1}(\frac{\alpha-\gamma}{1-\gamma})^{1-\gamma}]^{\frac{1}{\alpha-\gamma}}\}$ .

P r o o f. Assume that  $y(t)$  and  $x(t)$  are the solutions of IVP (1) on  $[t_0, t_0 + h]$ . Then

$$y(t) = x_0 + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} f(s, y(s)) ds, \quad t \in [t_0, t_0 + h]$$

and

$$x(t) = x_0 + \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} f(s, x(s)) ds, \quad t \in [t_0, t_0 + h].$$

Hence

$$\|y(t) - x(t)\| = \frac{1}{\Gamma(\alpha)} \left\| \int_{t_0}^t (t-s)^{\alpha-1} [f(s, y(s)) - f(s, x(s))] ds \right\|, \quad t \in [t_0, t_0 + h].$$

By (iv), we have

$$\|y(t) - x(t)\| \leq c \max_{s \in [t_0, t_0 + \delta]} \|y(s) - x(s)\|, \quad t \in [t_0, t_0 + h],$$

where  $c = \frac{M_1}{\Gamma(\alpha)} (\frac{1-\gamma}{\alpha-\gamma})^{1-\gamma} h^{\alpha-\gamma} \in (0, 1)$ . Therefore

$$\max_{s \in [t_0, t_0 + h]} \|y(t) - x(t)\| \leq c \max_{s \in [t_0, t_0 + h]} \|y(s) - x(s)\|, \quad t \in [t_0, t_0 + h]$$

which implies

$$x(t) \equiv y(t), \quad t \in [t_0, t_0 + h].$$

The proof is complete. ■



## References

- [1] V. Lakshmikantham, Theory of fractional functional differential equations. *Nonlinear Anal.* **69** (2008), 3337-3343.
- [2] V. Lakshmikantham and A.S. Vatsala, General uniqueness and monotone iterative technique for fractional differential equations. *Appl. Math. Lett.* **21** (2008), 828-834.
- [3] V. Lakshmikantham and A.S. Vatsala, Basic theory of fractional differential equations. *Nonlinear Anal.* **69** (2008), 2677-2682.
- [4] Wei Lin, Global existence theory and chaos control of fractional differential equations. *J. Math. Anal. Appl.*, **332** (2007), 709-726.
- [5] Yong Zhou, Existence and uniqueness of fractional functional differential equations with unbounded delay. *Int. J. Dyn. Syst. Differ. Equ.* **1**, No 4 (2008), 239-244.
- [6] M. Benchohra, J. Henderson, S.K. Ntouyas and A. Ouahab, Existence results for fractional order functional differential equations with infinite delay. *J. Math. Anal. Appl.* **338** (2008), 1340-1350.
- [7] R.W. Ibrahim and S. Momani, On the existence and uniqueness of solutions of a class of fractional differential equations. *J. Math. Anal. Appl.* **334**, No 1(2007), 1-10.
- [8] V. Daftardar-Gejji and H. Jafari, Analysis of a system of nonautonomous fractional differential equations involving Caputo derivatives. *J. Math. Anal. Appl.* **328** (2007), 1026-1033.
- [9] S.A. Messaoudi, B. Said-Houari and N.-E. Tatar, Global existence and asymptotic behavior for a fractional differential equation. *Applied Math. Comput.* **188** (2007), 1955-1962.
- [10] H.A.H. Salem, On the existence of continuous solutions for a singular system of non-linear fractional differential equations. *Applied Math. Comput.* **198**, No 1 (2008), 445-452.
- [11] M. Caputo, Linear models of dissipation whose  $Q$  is almost independent, II. *Geophys. J. R. Astron.* **13** (1967) 529-539.
- [12] W.G. Glöckle, T.F. Nonnenmacher, A fractional calculus approach to self similar protein dynamics. *Biophys. J.* **68** (1995), 46-53.
- [13] K. Diethelm, N.J. Ford, Analysis of fractional differential equations. *J. Math. Anal. Appl.* **265** (2002), 229-248.
- [14] K. Diethelm, N.J. Ford, Multi-order fractional differential equations and their numerical solution. *Appl. Math. Comp.* **154** (2004), 621-640.

- [15] K. Diethelm, A.D. Freed, On the solution of nonlinear fractional differential equations used in the modeling of viscoplasticity. In: F. Keil, W. Mackens, H. Vob, J. Werther (Eds.), *Scientific Computing in Chemical Engineering II: Computational Fluid Dynamics, Reaction Engineering, and Molecular Properties*, Heidelberg, Springer (1999), 217-224.
- [16] V. Kiryakova, *Generalized Fractional Calculus and Applications*. Pitman Res. Notes Math. Ser., vol. 301, Longman - Wiley, Harlow-New York (1994).
- [17] R. Metzler, W. Schick, H.G. Kilian, T.F. Nonnenmacher, Relaxation in filled polymers: A fractional calculus approach. *J. Chem. Phys.* **103** (1995), 7180-7186.
- [18] I. Podlubny, *Fractional Differential Equations*. Academic Press, San Diego (1999).
- [19] S.G. Samko, A.A. Kilbas, O.I. Marichev, *Fractional Integrals and Derivatives, Theory and Applications*. Gordon and Breach, Yverdon (1993).

*School of Math. and Comput. Sci.*  
*Xiangtan University*  
*Hunan 411105 – P.R. CHINA*  
*e-mail: yzhou@xtu.edu.cn*

*Received: November 26, 2008*